

**AMENDMENTS TO THE CLAIMS:**

The following listing of claims will replace all prior versions, and listings, of claims in the application:

Page 13, line 1, before claim 1, replace the single word heading CLAIMS with the following heading:

**CLAIMS WHAT IS CLAIMED IS:**

1. (Currently Amended) Tear-off device for sections ~~(48)~~ of a continuous material, comprising: ~~(18)~~ with

a pullout mechanism ~~(10)~~ for the transport of the continuous material ~~(18)~~ and with

a tear-off mechanism ~~(12)~~, which has at least two pressure-applying elements ~~(26, 56)~~, which are disposed on opposite sides of the continuous material ~~(18)~~ and a positioning device of which for engaging at least one said pressure-applying element can be positioned against the continuous material (18) by a positioning device, characterized in that the engagable pressure-applying elements (26, 56) are being constructed as eccentric rollers and being adapted to can be driven one of:

individually or and

jointly.

2. (Currently Amended) The tear-off device of claim 1,  
~~wherein characterized in that~~ the engagable pressure-applying  
elements have internal eccentrics ~~(28, 30)~~, which are adapted to  
~~can~~ be rotated and on which the pressure-applying rollers ~~(26)~~  
are mounted rotatably.

3. (Currently Amended) The tear-off device of claim 1,  
~~wherein characterized in that~~ the engagable, pressure-applying  
elements ~~(56)~~ have cams ~~(58)~~, which are adapted to ~~can~~ be engaged  
against the continuous material ~~(18)~~.

4. (Currently Amended) The tear-off device of claim 3,  
~~wherein characterized in that~~ the cams ~~(58)~~ have the shape of  
roller segments.

5. (Currently Amended) The tear-off device of claim 1,  
~~wherein one of the preceding claims, characterized in that~~ the  
positioning device has at least one motor ~~(36)~~, by means of which  
for driving the pressure-applying elements ~~(26, 56)~~ can be  
driven.

6. (Currently Amended) The tear-off device of claim 5,  
~~wherein characterized in that~~ the positioning device has a  
control device ~~(42)~~ for the temporal control of ~~the~~ movement of

the motor (36).

7. (Currently Amended) The tear-off device of claim 6, wherein characterized in that the control device (42) is a programmable control device, with which the for adjusting points in time of the at least one of engagement and/or withdrawal movements can be adjusted in relation to the transport of the continuous material (18).

8. (Currently Amended) The tear-off device of claim 6, one of the claims 6 or 7, wherein characterized in that the at least one motor (36) of the positioning device is adapted to can be driven over a limited traversing distance in opposite directions and the adjusting movements of the at least one motor (36) can are adapted to be controlled temporally by the control device (42) and, in the case of a programmable control device (42), the traversing distance of the motor (36) can be programmed.

9. (Currently Amended) The tear-off device of claim 5, wherein one of the claims 5 to 7, characterized in that the at least one motor (36) can is adapted to be driven in one direction of rotation with a variable speed.

10. (Currently Amended) The-tear off device of claim 9,  
~~characterized in that~~ wherein the speed of the at least one motor  
(36) ~~can~~ is adapted to be varied down to zero.

11. (Currently Amended) The-tear off device of claim 5, one  
~~of the claims 5 to 10, characterized in that~~ wherein the at least  
one motor (36) is a servomotor.

12. (Currently Amended) The tear-off device of claim 1,  
~~wherein one of the preceding claims, characterized in that~~ the  
pullout mechanism (10) and the tear-off mechanism (12) each have  
their own driving mechanism (22).

13. (Currently Amended) The tear-off device of claim 1,  
~~wherein one of the preceding claims, characterized in that~~ the  
positioning device has at least one displaceable frame (32), in  
which at least one ~~or more~~ pressure-applying element is elements  
(26, 56) ~~are~~ mounted.

14. (New) The tear-off device of one of the claim 8,  
wherein the control device is a programmable control device for  
controlling a traversing distance of the at least one motor.